



Ensemble Data Assimilation in NEMO using PDAF

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PDAF Parallel
Data Assimilation
Framework

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PDAF – Parallel Data Assimilation Framework

A unified tool for interdisciplinary data assimilation ...

- provide support for parallel ensemble forecasts
- provide assimilation methods (solvers) - fully-implemented & parallelized
- provide tools for observation handling and for diagnostics
- easily useable with (probably) any numerical model
- a program library (PDAF-core) plus additional functions
- run from notebooks to supercomputers (Fortran, MPI & OpenMP)
- ensure separation of concerns (model – DA method – observations – covariances)

Open source:
Code, documentation, and tutorial available at
<http://pdaf.awi.de>

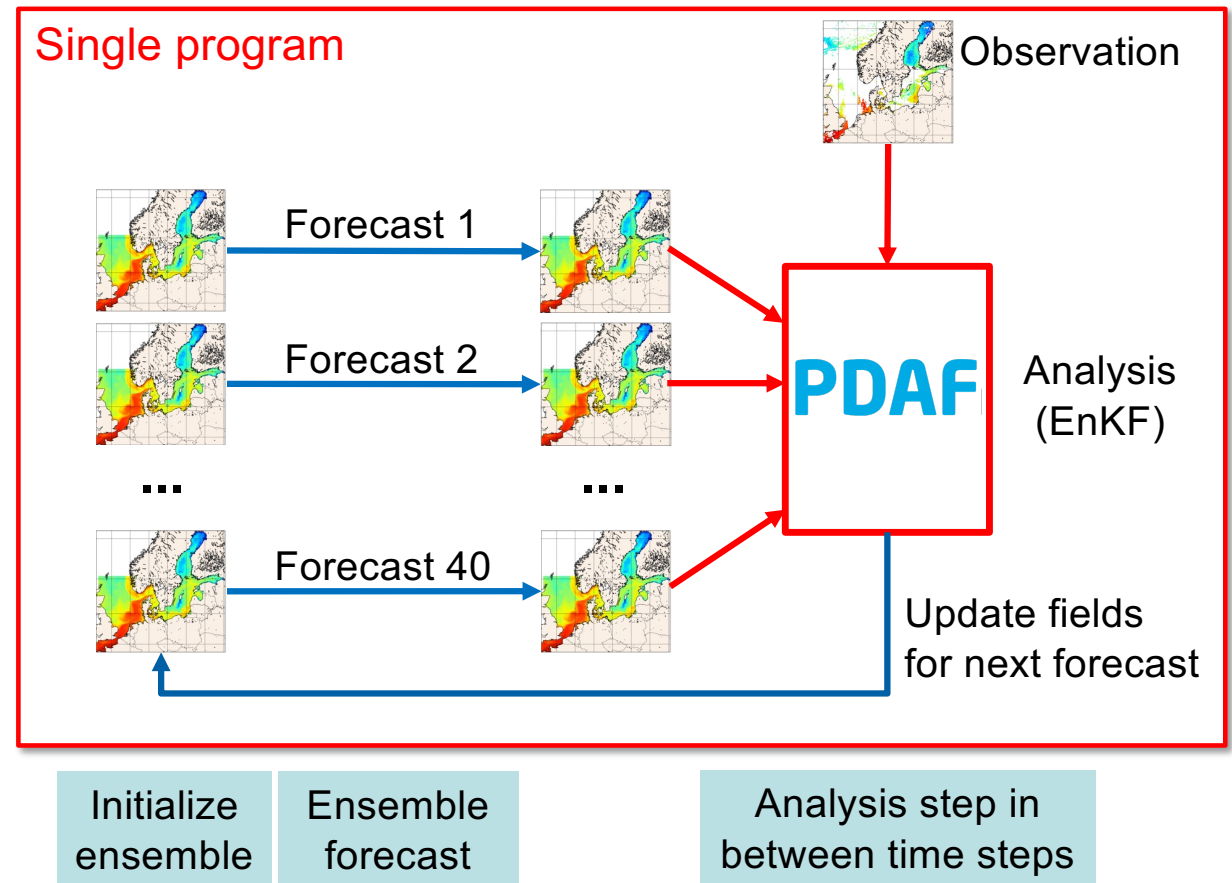


Online-Coupling – Assimilation-enabled Model

Couple a model with PDAF

- Modify model to simulate ensemble of model states
- Insert analysis step/solver to be executed at prescribed interval
- Run model as usual, but with more processors and additional options

- EnOI and 3D-Var also possible:
 - Evolve single model state
 - Prescribe ensemble perturbations or covariance



NEMO-PDAF Online Coupling

Model code

DA code

PDAF Parallel
Data Assimilation
Framework

Augment NEMO with DA functionality

- Insert 4 subroutine calls
- Modify parallelization for ensemble mode
- Transfer data between model and PDAF in memory
- Adapt NEMO's ASM module: PDAF provides increments in memory
- No changes to XIOS, but to file_def*.xml

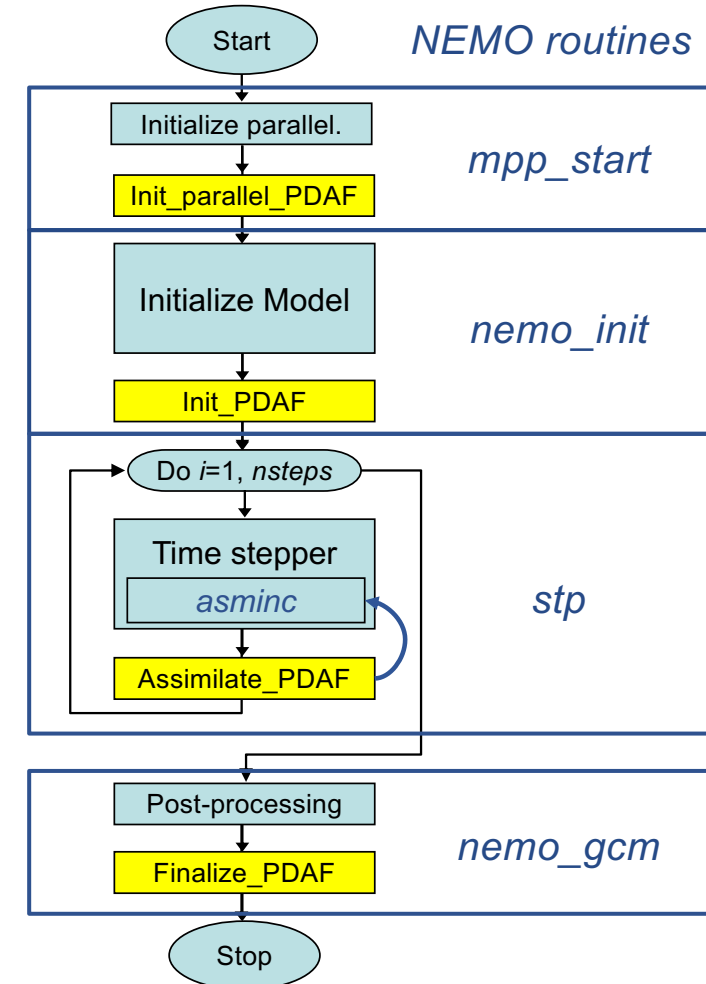
- Very efficient & highly scalable
- Direct access to model grid and fields through Fortran modules
- File output kept to minimum
- No model restarts for cycled assimilation

Change parallelization for ensemble run

Initialize PDAF and ensemble

Analysis step

Deallocate & timing/memory info



PDAF interface structure

- **Model-sided Interface:** Defined calls to PDAF routines
(called by driver program for offline coupling)
- **Case-related Interface:**
User-supplied call-back routines for elementary operations:
 - transfers between model fields and ensemble of state vectors
 - observation-related operations
- User-supplied routines can be implemented as routines of the model and can share data with it (low abstraction level)

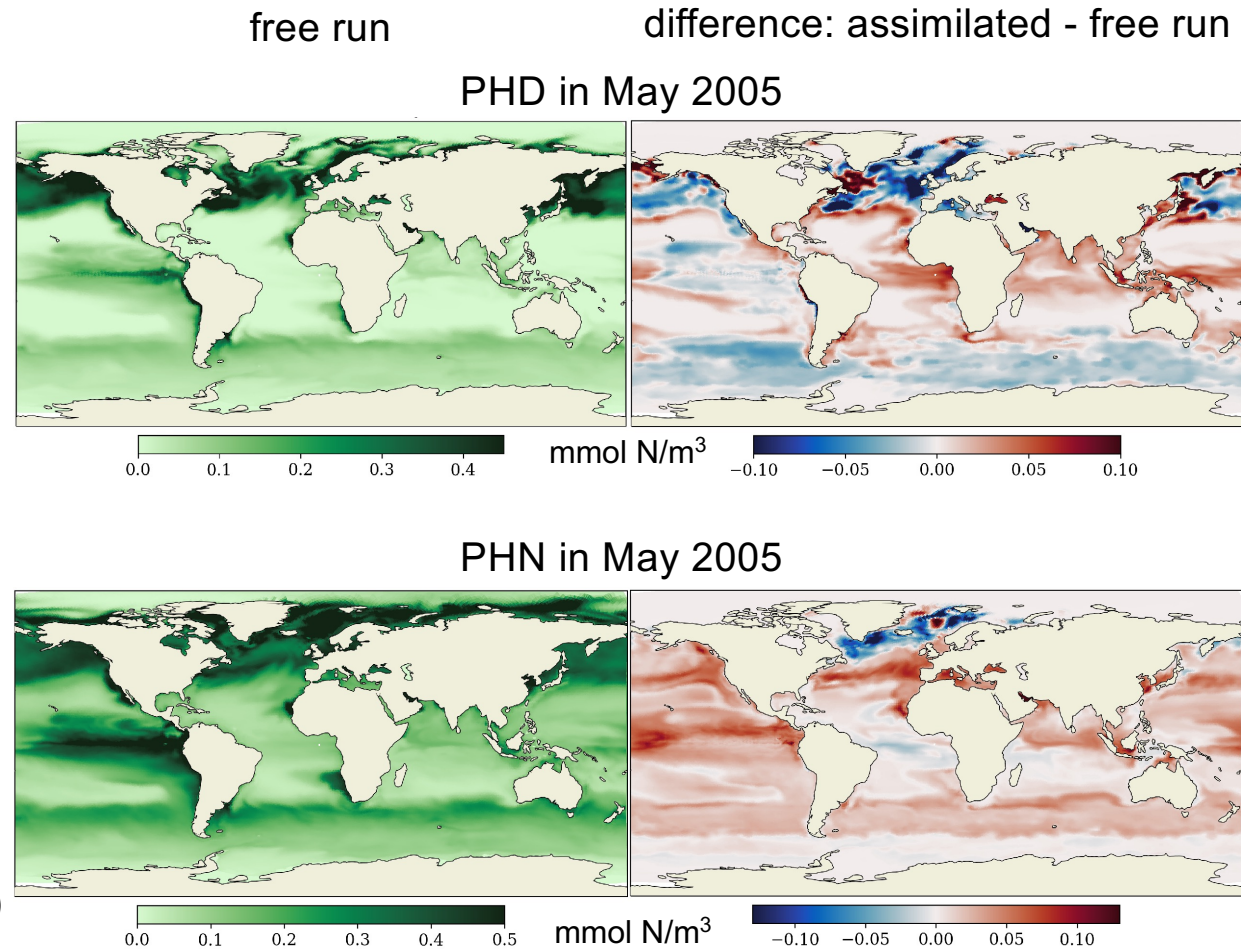


Online: Access model information through modules / static variables

offline: initialize model information from files

Assimilating Phytoplankton Carbon in NEMO-FABM-MEDUSA

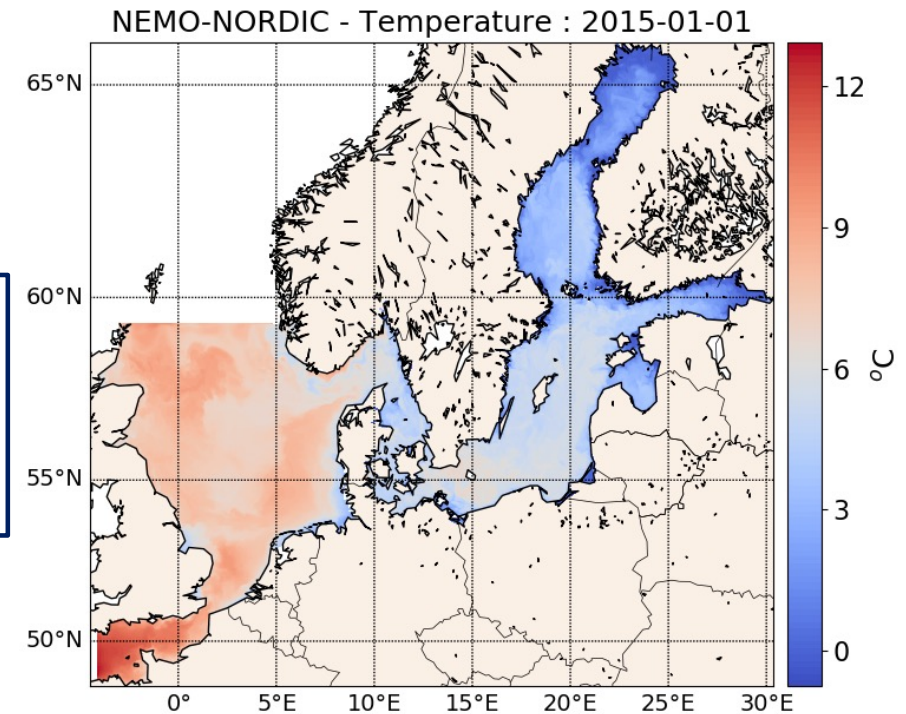
- DA setup
 - Kalman filter: LESTKF
 - Localisation radius: 200 km
 - Forgetting factor: 0.95
 - Ensemble size: 30
- Model setup
 - FABM-MEDUSA
 - ORCA1 grid
 - Year: 2005
- Observation
 - The phytoplankton carbon products from BICEP project
- State
 - Diatom phytoplankton nitrogen (PHD)
 - non-diatom phytoplankton nitrogen (PHN)



Assimilating SST and Chlorophyll in NEMO-ERGOM

- Model setup
 - NEMO-NORDIC + ERGOM biogeochemistry
 - 1 nm resolution (ca. 1.8km); 56 layers
 - Year: 2015
- DA setup
 - Kalman filter: LESTKF
 - Localisation radius: 15 km
 - Forgetting factor: 0.95
 - Ensemble size: 30
 - Daily assimilation
- Observations
 - SST and Chlorophyll from CMEMS
- State
 - 5 physics variables
 - 16 ERGOM prognostic variables + 4 diagnostic variables
 - State dimension: $704 \cdot 10^6$

Poster:
Sun & Nerger
Today OS4.11
Board X5.306



Summary – NEMO-PDAF

- Coupled NEMO and PDAF for (ensemble) data assimilation
 - state vector can include ocean physics / sea ice / BGC ...
 - easy addition of observation types
 - supports cycled DA without model restarts
 - utilize NEMO's ASM-module: IAU and direct initialization
 - Currently for NEMO 4.0.x – NEMO 4.2 in progress
- Code will be made open source



PDAF is open source:
Code, documentation, and tutorial available at
<http://pdaf.awi.de>

PDAF package: DA Algorithms and Models

PDAF originated from comparison studies of different filters

Ensemble Filters and smoothers - *global and localized*

- EnKF (Evensen, 1994 + perturbed obs.)
- (L)ETKF (Bishop et al., 2001/Hunt et al. 2007)
- ESTKF (Nerger et al., 2012)
- NETF (Toedter & Ahrens, 2015)
- Particle filter
- *EnOI mode*

Model bindings

- MITgcm
- AWI-CM / FESOM

Toy models (full implementations with PDAF)

- Lorenz-96 / Lorenz-63
- Lorenz-2005 models II and III

3D-Var schemes

(incremental with control variable transformation)

- 3D-Var with parameterized covar.
- 3D Ensemble Var
- Hybrid 3D-Var

Community:

- pyPDAF (Python-coded models)
- TerrSysMP-PDAF

In progress

- SCHISM/ESMF (VIMS)
- GOTM/FABM “EAT” (BB ApS)

References

- <https://pdaf.awi.de> (The website also provides a list of studies using PDAF)
- <https://github.com/PDAF>
- Nerger, L., Hiller, W. (2013). Software for Ensemble-based Data Assimilation Systems - Implementation Strategies and Scalability. Computers and Geosciences, 55, 110-118. [doi:10.1016/j.cageo.2012.03.026](https://doi.org/10.1016/j.cageo.2012.03.026)
- Nerger, L., Hiller, W., Schröter, J.(2005). PDAF - The Parallel Data Assimilation Framework: Experiences with Kalman Filtering, Use of high performance computing in meteorology : proceedings of the Eleventh ECMWF Workshop on the Use of High Performance Computing in Meteorology, Reading, UK, 25 - 29 October 2004 / Eds.: Walter Zwiefelhofer; George Mozdzyński, Singapore: World Scientific, 63-83. [doi:10.1142/9789812701831_0006](https://doi.org/10.1142/9789812701831_0006)
- Nerger, L., Tang, Q., Mu, L. (2020). Efficient ensemble data assimilation for coupled models with the Parallel Data Assimilation Framework: Example of AWI-CM. Geoscientific Model Development, 13, 4305–4321, [doi:10.5194/gmd-13-4305-2020](https://doi.org/10.5194/gmd-13-4305-2020)

